

Improving Retinal Prosthetics Through Artificial Intelligence

Jacob Perala

University of Minnesota Morris

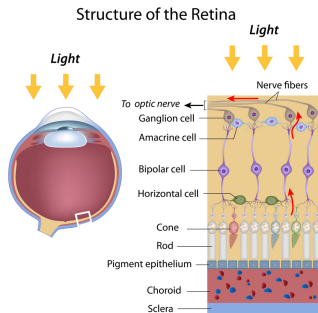
November 13, 2021

Outline

- Background
 - ▶ Relevant Biology of The Retina
 - ▶ System Structures of A Retinal Prosthetic
 - ▶ Image Analysis Techniques With AI
- Understanding Digital Media With AI
- AI In Retinal Prosthetics

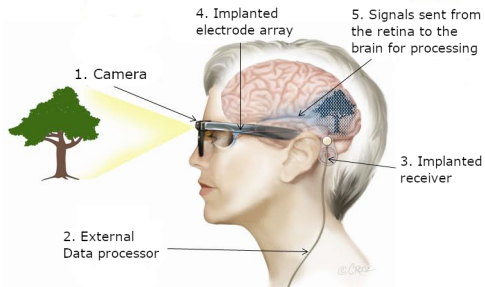
The Retina

- Responsible for receiving and processing light
- The photoreceptive layer is composed of rods and cones, responsible for sensing light
- Ganglion cells in the retina output signals to the brain



Retinal Prosthetic System Structure

- Camera
- Telemetry unit
- Processing device
- Electrode implant



Simulating Vision of Retinal Prosthetic Patients

- Simulates the visual experience of a patient with a retinal prosthetic
- Pulse-2-Percept
- Phosphenification



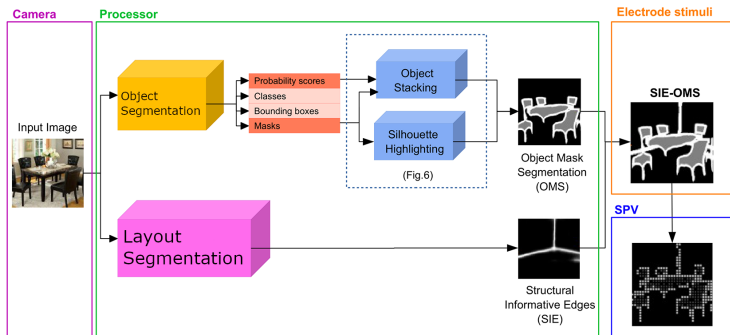
Image Segmentation

- Partitions an object in an image into sets of segments
- Relies on edge detection techniques to define contours



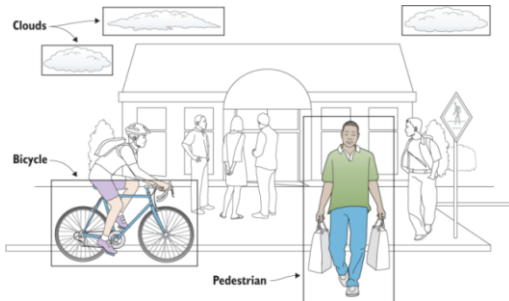
Scene Reconstruction

- Uses segmented objects and layouts to construct a scene
- Indoor scenes pose different challenges from outdoor scenes



Object Detection & Recognition

- Detects objects in a scene
- Process responsible for identifying objects
- Objects have differing importance in detail (i.e. cars vs faces)

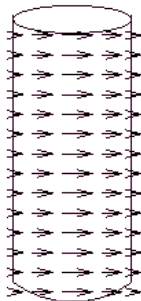


Optical Flow & Motion Estimation

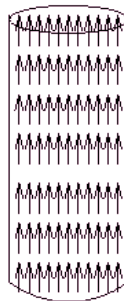
- Used to determine the apparent movement of objects in a scene
- Estimates motion by pixel brightness or feature tracking



Barber's Pole



Motion Field



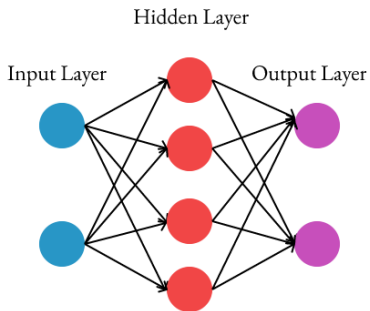
Optical Flow

Outline

- Background
- Understanding Digital Media With AI
 - ▶ Neural Networks
 - ▶ Computer Vision
- AI In Retinal Prosthetics

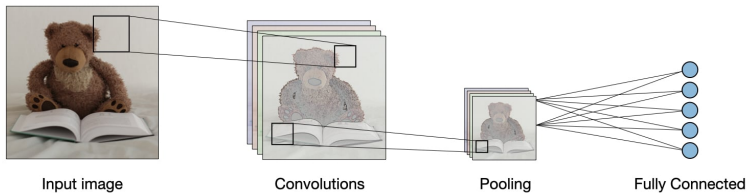
Neural Networks (1/2)

- Named after and follows the structure of the human brain
- Used to classify and find patterns in data



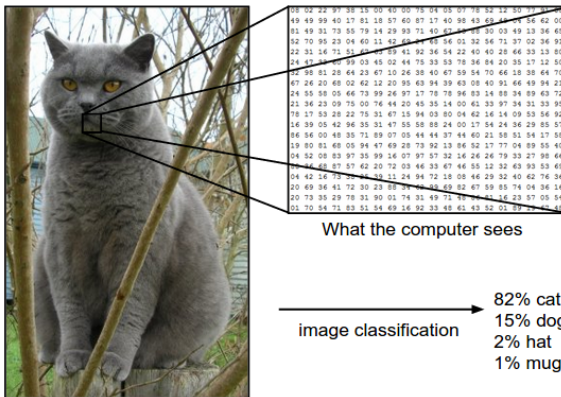
Neural Networks (2/2)

- Deep learning is a classification of neural networks
- Convolutional Neural Networks



Computer Vision

- Made to mimic the human visual system
- Uses AI to find patterns to determine the content of an image



Applying AI to Improve Artificial Vision

- Improving image segmentation speed and accuracy
- Identifying objects and avoiding collisions
- Expanding scene reconstruction capability

Condition	Accuracy	Precision
Saliency	0.51	0.53
Depth	0.54	0.56
Segmentation	0.68	0.73
Combination	0.66	0.72

Figure: Table 1. Based on Han et al., 2021

Classification Methods	Overall Accuracy(%)
Adaboost	77.50
MLP	32.50
SVM	61.25
NeuCube	90.50

Figure: Table 1. Based on Ge et al., 2017

Future Work

- Computation of moving and occluded objects
- Prioritization of objects in a scene
- Variations in environments

References I

- Amidi, A., & Amidi, S. (n.d.). Convolutional neural networks cheatsheet.
- Ayton, L. N., Barnes, N., Dagnelie, G., Fujikado, T., Goetz, G., Hornig, R., Jones, B. W., Muqit, M., Rathbun, D. L., Stingl, K., Weiland, J. D., & Petoe, M. A. (2020). An update on retinal prostheses. *International Federation of Clinical Neurophysiology*, 131(6), 1383–1398.
- Beyeler, M., Boynton, G., Fine, I., & Rokem, A. (2017). Pulse2percept: A python-based simulation framework for bionic vision.
<https://doi.org/10.25080/shinma-7f4c6e7-00c>
- Elgendy, M. (2020). *Deep learning for vision systems*.

References II

- Ge, C., Kasabov, N., Liu, Z., & Yang, J. (2017). A spiking neural network model for obstacle avoidance in simulated prosthetic vision. *Information Sciences*, 399, 30–42.
<https://doi.org/https://doi.org/10.1016/j.ins.2017.03.006>
- Guo, F., Yang, Y., Xiao, Y., Gao, Y., & Yu, N. (2019). Recognition of moving object in high dynamic scene for visual prosthesis. *IEICE TRANSACTIONS on Information and Systems*, E102-D, 1321–1331.
<https://doi.org/10.1587/transinf.2018EDP7405>
- Han, N., Srivastava, S., Xu, A., Klein, D., & Beyeler, M. (2021). Deep learning–based scene simplification for bionic vision. *Augmented Humans Conference 2021*, 45–54.
<https://doi.org/10.1145/3458709.3458982>

References III

- Sanchez-Garcia, M., Martinez-Cantin, R., & Guerrero, J. J. (2020). Semantic and structural image segmentation for prosthetic vision (1st ed.). *PLoS ONE*, 15. <https://journals.plos.org/plosone/article?id=10.1371/journal.pone.0227677>
- University, S. (n.d.). Cs231n: Convolutional neural networks for visual recognition.